

14.461: Technological Change, Lecture 9

Climate Change and Technology

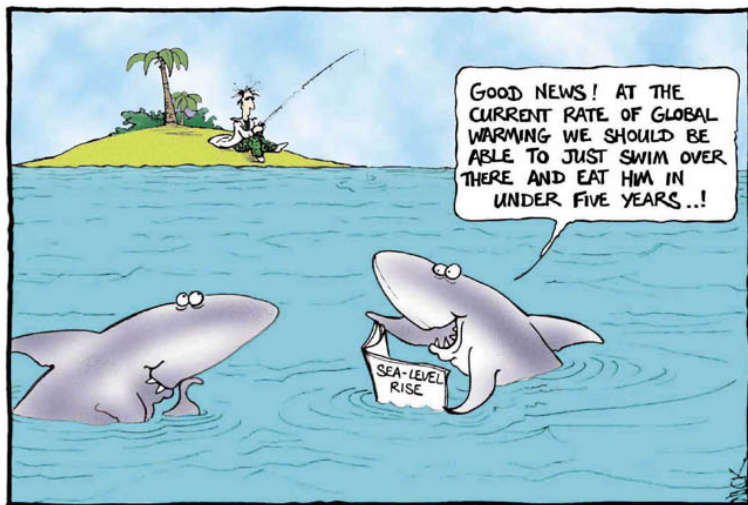
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Motivation (I)

- Consensus about climate change due greenhouse gas emissions.



Motivation (II)



- But also increasing recognition that most of the action will come to transition to clean technology.
- How to switch to clean technology in a “welfare maximizing” way?

Motivation (III)

- Empirical work: possible switch away from dirty to clean technologies in response to changes in prices and policies.
 - Newell, Jaffe and Stavins (1999):
 - following the oil price hikes, innovation in air-conditioners towards more energy efficient units
 - Popp (2002):
 - higher energy prices associated with a significant increase in energy-saving innovations
 - Hassler, Krusell and Olovsson (2011):
 - trend break in energy-saving factor productivities after high oil prices
 - Aghion et al. (2012):
 - significant impact of carbon taxes on the direction of innovation in the automobile industry.

Motivation (III)

- A systematic investigation necessitates:
 - micro model
 - with carbon emissions and potential climate change,
 - where clean and dirty technologies compete, and
 - research incentives (and the direction of technological change) are endogenous.
 - micro data
 - for the modeling of competition in production and innovation,
 - quantitative analysis
 - to study the impacts of various policies.
- This lecture: two models—first about the conceptual issues (less micro and no data) and the second more about micro structure of technology choices, estimation and quantitative analysis.

Exogenous Growth Approaches

- Economic analyses using computable general equilibrium models with exogenous technology (and climatological constraints; e.g., Nordhaus, 1994, 2002).
- Key issues for economic analyses: (1) economic costs and benefits of environmental policy; (2) costs of delaying intervention (3) role of discounting and risk aversion.
- Various conclusions:
 - ① **Nordhaus approach:** intervention should be limited and gradual; small long-run growth costs.
 - ② **Stern/Al Gore approach:** intervention needs to be large, immediate and maintained permanently; large long-run growth costs.
 - ③ **Greenpeace approach:** only way to avoid disaster is zero growth.

Endogenous and directed technology

- Very different answers are possible.
 - 1 Immediate and decisive intervention is necessary (in contrast to Nordhaus)
 - 2 Temporary intervention may be sufficient (in contrast to Stern/Al Gore)
 - 3 Long-run growth costs may actually be very limited (in contrast to all of them).
 - 4 Two instruments—not one—necessary for optimal environmental regulation.

Why?

- Two sector model with “clean” and “dirty” inputs with two key externalities
- *Environmental externality*: production of dirty inputs creates environmental degradation.
- Researchers work to improve the technology depending on expected profits and **“build on the shoulders of giants in their own sector”**.
 - *Knowledge externality*: advances in dirty (clean) inputs make their future use more profitable.
- Policy interventions can **redirect technological change** towards clean technologies.

Why? (Continued)

- ① Immediate and decisive intervention is necessary (in contrast to Nordhaus)
 - without intervention, innovation is directed towards dirty sectors; thus gap between clean and dirty technology widens; thus cost of intervention (reduced growth when clean technologies catch up with dirty ones) increases
- ② Temporary intervention may be sufficient (in contrast to Stern/Al Gore), long-run growth costs limited (in contrast to all of them)
 - once government intervention has induced a technological lead in clean technologies, firms will spontaneously innovate in clean technologies (if clean and dirty inputs are sufficiently substitutes).
- ③ Two instruments, not one:
 - optimal policy involves both a carbon tax and a subsidy to clean research to redirect innovation to green technologies
 - too costly in terms of foregone short-run consumption to use carbon tax alone

Model (1): production

- Infinite horizon in discrete time (suppress time dependence for now)
- Final good Y produced competitively with a clean intermediary input Y_c , and a dirty input Y_d

$$Y = \left(Y_c^{\frac{\varepsilon-1}{\varepsilon}} + Y_d^{\frac{\varepsilon-1}{\varepsilon}} \right)^{\frac{\varepsilon}{\varepsilon-1}}$$

- Most of the analysis: $\varepsilon > 1$, the two inputs are substitute.
- For $j \in \{c, d\}$, input Y_j produced with labor L_j and a continuum of machines x_{ji} :

$$Y_j = L_j^{1-\alpha} \int_0^1 A_{ji}^{1-\alpha} x_{ji}^{\alpha} di$$

- Machines produced **monopolistically** using the final good

Model (2): consumption

- Constant mass 1 of infinitely lived representative consumers with intertemporal utility:

$$\sum_{t=0}^{\infty} \frac{1}{(1+\rho)^t} u(C_t, S_t)$$

where u increasing and concave, with

$$\lim_{S \rightarrow 0} u(C, S) = -\infty; \frac{\partial u}{\partial S}(C, \bar{S}) = 0$$

Model (3): environment

- Production of dirty input depletes environmental stock S :

$$S_{t+1} = -\xi Y_{dt} + (1 + \delta) S_t \quad \text{if } S \in (0, \bar{S}) . \quad (1)$$

- Reflecting at the upper bound \bar{S} ($< \infty$): baseline (unpolluted) level of environmental quality.
- Absorbing at the lower bound $S = 0$.
- $\delta > 0$: rate of “environmental regeneration” (measures amount of pollution that can be absorbed without extreme adverse consequences)
- S is general quality of environment, inversely related to CO2 concentration (what we do below for calibration).

Model (4): innovation

- At the beginning of every period scientists (of mass $s = 1$) work either to innovate in the clean or the dirty sector.
- Given sector choice, each randomly allocated to one machine in their target sector.
- Every scientist has a probability η_j of success (without congestion).
 - if successful, proportional improvement in quality by $\gamma > 0$ and the scientist gets monopoly rights for one period, thus

$$A_{jit} = (1 + \gamma) A_{jit-1};$$

- if not successful, no improvement and monopoly rights in that machine randomly allocated to an entrepreneur who uses technology

$$A_{jit} = A_{jit-1}.$$

- simplifying assumption, mimicking structure in continuous time models.

Model (5): innovation (continued)

- Therefore, law of motion of quality of input in sector $j \in \{c, d\}$ is:

$$A_{jt} = \left(1 + \gamma \eta_j s_{jt}\right) A_{jt-1}$$

- **Note:** *knowledge externality*; “building on the shoulders of giants,” but importantly “**in own sector**”—*extreme state dependence*.
 - Intuition: Fuel technology improvements do not directly facilitate discovery of alternative energy sources

Assumption

A_{d0} sufficiently higher than A_{c0} .

- Capturing the fact that currently fossil-fuel technologies are more advanced than alternative energy/clean technologies.

Laissez-faire equilibrium: direction of innovation

- Scientists choose the sector with higher expected profits Π_{jt} :

$$\frac{\Pi_{ct}}{\Pi_{dt}} = \frac{\eta_c}{\eta_d} \underbrace{\left(\frac{p_{ct}}{p_{dt}} \right)^{\frac{1}{1-\alpha}}}_{\text{price effect}} \underbrace{\frac{L_{ct}}{L_{dt}}}_{\text{market size effect}} \underbrace{\frac{A_{ct-1}}{A_{dt-1}}}_{\text{direct productivity effect}}$$

- The direct productivity effect pushes towards innovation in the more advanced sector
- The price effect towards the less advanced, price effect stronger when ε smaller
- The market size effect towards the more advanced when $\varepsilon > 1$

Laissez-faire equilibrium (continued)

- Use equilibrium machine demands and prices in terms of technology levels (state variables) and let $\varphi \equiv (1 - \alpha)(1 - \varepsilon)$ (< 0 if $\varepsilon > 1$):

$$\frac{\Pi_{ct}}{\Pi_{dt}} = \frac{\eta_c}{\eta_d} \left(\frac{1 + \gamma\eta_c s_{ct}}{1 + \gamma\eta_d s_{dt}} \right)^{-\varphi-1} \left(\frac{A_{ct-1}}{A_{dt-1}} \right)^{-\varphi}.$$

- **Implications:** innovation in relatively advanced sector if $\varepsilon > 1$

Laissez-faire equilibrium production levels

- Equilibrium input production levels

$$Y_d = \frac{1}{(A_c^\varphi + A_d^\varphi)^{\frac{\alpha+\varphi}{\varphi}}} A_c^{\alpha+\varphi} A_d;$$

$$Y = \frac{A_c A_d}{(A_c^\varphi + A_d^\varphi)^{\frac{1}{\varphi}}}$$

- Recall that $\varphi \equiv (1 - \alpha)(1 - \varepsilon)$.
- In particular, given the assumption that A_{d0} sufficiently higher than A_{c0} , Y_d will always grow without bound under laissez-faire
 - If $\varepsilon > 1$, then all scientists directed at dirty technologies, thus $g_{Y_d} \rightarrow \gamma \eta_d$

Environmental disaster

- An environmental “**disaster**” occurs if S_t reaches 0 in finite time.

Proposition

Disaster.

The laissez-faire equilibrium always leads to an environmental disaster.

Proposition

The role of policy.

- ① *when the two inputs are strong substitutes ($\varepsilon > 1 / (1 - \alpha)$) and \bar{S} is sufficiently high, a temporary clean research subsidy will prevent an environmental disaster;*
- ② *in contrast, when the two inputs are weak substitutes ($\varepsilon < 1 / (1 - \alpha)$), a temporary clean research subsidy cannot prevent an environmental disaster.*

Sketch of proof

- Look at effect of a temporary clean research subsidy
- Key role: **redirecting technological change**; innovation can be redirected towards clean technology
- If $\varepsilon > 1$, then subsequent to an extended period of taxation, innovation will remain in clean technology
- Is this sufficient to prevent an environmental disaster?

Sketch of proof (continued)

- Even with innovation only in the clean sector, production of dirty inputs may increase
 - *on the one hand*: innovation in clean technology reduces labor allocated to dirty input $\Rightarrow Y_d \downarrow$
 - *on the other hand*: innovation in clean technology makes final good cheaper an input to production of dirty input $\Rightarrow Y_d \uparrow$
 - which of these two effects dominates, will depend upon ε .
- With clean research subsidy (because $\varepsilon > 1$ and thus $\varphi < 0$):

$$Y_d = \frac{1}{(A_c^\varphi + A_d^\varphi)^{\frac{\alpha+\varphi}{\varphi}}} A_c^{\alpha+\varphi} A_d \rightarrow A_c^{\alpha+\varphi}$$

- If $\alpha + \varphi > 0$ or $\varepsilon < 1/(1 - \alpha)$, then second effect dominates, and long run growth rate of dirty input is positive equal to $(1 + \gamma\eta_c)^{\alpha+\varphi} - 1$
- If $\alpha + \varphi < 0$ or $\varepsilon > 1/(1 - \alpha)$, then first effect dominates, so that Y_d decreases over time.

Cost of intervention and delay

- Concentrate on strong substitutability case ($\varepsilon > 1/(1 - \alpha)$)
- While A_{ct} catches up with A_{dt} , growth is reduced.
- T : number of periods necessary for the economy under the policy intervention to reach the same level of output as it would have done within one period without intervention
- If intervention delayed, not only the environment gets further degraded, but also technology gap A_{dt-1}/A_{ct-1} increases, growth is reduced for a longer period.
- More generally, significant welfare costs from delay (based on calibration).

Undirected technical change

- Compare with a model where scientists randomly allocated across sectors so as to ensure equal growth in the qualities of clean and dirty machines, thus $g_{Y_d} \rightarrow \gamma \eta_c \eta_d / (\eta_c + \eta_d) < \gamma \eta_d$

Proposition

The role of directed technical change.

When $\varepsilon > 1/(1 - \alpha)$:

- 1 *An environmental disaster under laissez-faire arises earlier with directed technical change than in the equivalent economy with undirected technical change.*
- 2 *However, a temporary clean research subsidy can prevent an environmental disaster with directed technical change, but not in the equivalent economy with undirected technical change.*

Optimal environmental regulation

Proposition

Optimal environmental regulation.

A planner can implement the social optimum through a "carbon tax" on the use of the dirty input, a clean research subsidy and a subsidy for the use of all machines (all taxes/subsidies are financed by lumpsum taxes).

- ① *If $\varepsilon > 1$ and the discount rate ρ is sufficiently small, then in finite time innovation ends up occurring only in the clean sector, the economy grows at rate $\gamma\eta_c$ and the optimal subsidy to clean research, q_t , is temporary.*
 - ② *The optimal carbon tax, τ_t , is temporary if $\varepsilon > 1/(1 - \alpha)$ but not if $1 < \varepsilon < 1/(1 - \alpha)$.*
- Interpretation: two instruments for two margins—carbon tax for the intra-temporal one and research subsidies for the intertemporal one. But importantly, both are **temporary**.

Carbon tax

- Optimal carbon tax schedule is given by

$$\tau_t = \frac{\omega_{t+1}\tilde{\zeta}}{\lambda_t p_{dt}},$$

- λ_t is the marginal utility of a unit of consumption at time t
- ω_{t+1} is the shadow value of one unit of environmental quality at time $t + 1$, equal to the discounted marginal utility of environmental quality as of period $t + 1$.
- *Why temporary?* If $\varepsilon > 1/(1 - \alpha)$, dirty input production tends towards 0 and environmental quality S_t reaches \bar{S} in finite time and thus $\omega_t \rightarrow 0$, carbon tax becomes null in finite time.
- *Why two instruments?* If gap between the two technologies is high, relying on carbon tax to redirect technical change would reduce too much consumption.

Exhaustible resources

- Polluting activities (CO2 emissions) often use an exhaustible resource (most importantly, oil).
- Dirty input produced with some exhaustible resource R :

$$Y_d = R^{\alpha_2} L_d^{1-\alpha} \int_0^1 A_{di}^{1-\alpha_1} x_{di}^{\alpha_1} di,$$

with $\alpha_1 + \alpha_2 = \alpha$.

- The resource stock Q_t evolves according to

$$Q_{t+1} = Q_t - R_t$$

- Extracting 1 unit of resource costs $c(Q_t)$ (with $c' \leq 0$, $c(0)$ finite). As Q_t decreases, extracting the resource becomes increasingly costly.

Main results

- With exhaustible resources, environmental disaster could be averted without policy intervention because increasing prices of the scarce exhaustible resources could automatically redirect technological change.
- Nevertheless, optimal policy very similar with or without exhaustible resources.

Two-country case

- Two countries: North (N), identical to the economy studied so far, and that the South (S) imitating Northern technologies.
- Thus there are two externalities:
 - ① *environmental externality*: dirty input productions by both contribute to global environmental degradation

$$S_{t+1} = -\xi \left(Y_{dt}^N + Y_{dt}^S \right) + (1 + \delta) S_t \text{ for } S \in (0, \bar{S}).$$

- ② *knowledge externality*: South imitates North' technologies.
- Do we need global coordination to avert an environmental disasters?
 - In autarky, the answer is no because advances in the North will induce the South to also switch to clean technologies.
 - But free trade may undermine this result by creating **pollution havens**—the South specializes even more in dirty technologies because of environmental policy in the North.

Modeling competition between clean and dirty technologies

- Now a more micro-based model of competition between clean and dirty technologies that can be estimated from firm-level data (for the energy sector in the United States) on
 - R&D expenditures,
 - patents,
 - sales,
 - employment,
 - firm entry and exit.
- Data sources:
 - Longitudinal Business Database and Economic Censuses,
 - the National Science Foundation's Survey of Industrial R&D,
 - the NBER Patent Database.
- Also, a more realistic model of the carbon cycle.
- This will allow more systematic counterfactual policy experiments.

Preferences

- Infinite-horizon economy in continuous time.
- Representative household:

$$U = \int_0^{\infty} \exp(-\rho t) \ln C_t dt.$$

- Inelastic labor supply, no occupational choice:
 - Unskilled labor: for production: measure 1, earns w_t^u
 - Skilled labor: measure L^s , earns w_t^s .
 - cover fixed and variable costs of R&D.
- Hence the budget constraint is

$$C_t \leq w_t^u + L^s \cdot w_t^s + \Pi_t$$

- Closed economy and no investment, resource constraint: $Y_t = C_t$.

Final Good Technology

- Unique final good Y_t :

$$\ln Y_t = -\gamma (S_t - \bar{S}) + \int_0^1 \ln y_{it} di,$$

y_{it} : quantity of intermediate good i .

$S_t \geq \bar{S}$: atmospheric carbon concentration.

$\bar{S} > 0$: preindustrial level.

Intermediate Good Technology (I)

- Intermediate good y_{it} :

$$y_{it} = \begin{cases} y_{it}^c & \text{with **clean** technology, or} \\ y_{it}^d & \text{with **dirty** technology} \end{cases}$$

Intermediate Good Technology (II)

- Firm f can produce intermediate i with either a clean or dirty, $j \in \{c, d\}$:

$$y_{it}^j(f) = q_{it}^j(f) l_{it}^j(f)$$

- $l_{it}^j(f)$: production workers
 - $q_{it}^j(f)$: labor productivity.
- marginal cost of production is

$$MC_{it}^j = \left(1 + \tau_t^j\right) \frac{w_t^u}{q_{it}^j}$$

where τ_t^j is the tax rate on technology j .

Intermediate Good Technology (III)

- Produce with technology $j \in \{c, d\}$ if

$$\frac{(1 + \tau_t^{-j}) w_t^u}{q_{it}^{-j}} > \frac{(1 + \tau_t^j) w_t^u}{q_{it}^j}$$

- i.e., produce with **dirty** technology iff

$$\frac{q_{it}^d}{q_{it}^c} > \frac{1 + \tau_t^d}{1 + \tau_t^c}.$$

Quality Ladder

- Innovations improve quality by multiples of $\lambda > 1$.
- n_{it}^j improvements leads to

$$q_{it}^j = \lambda^{n_{it}^j},$$

where $q_{i0}^j = 1$.

- Hence

$$\frac{q_{it}^d}{q_{it}^c} = \lambda^{n_{it}}$$

$$n_{it} \equiv n_{it}^d - n_{it}^c.$$

- Define μ_n : fraction of n -step industries.

Carbon Tax

- For tractability, tax rates are:

$$1 + \tau_t^j = \lambda^{m_t^j}.$$

- Hence:

$$\frac{1 + \tau_t^d}{1 + \tau_t^c} = \lambda^{m_t},$$

where $m_t \equiv m_t^d - m_t^c$.

Production Decision

- Produce with technology $j = \text{dirty}$ if

$$\frac{q_{it}^d}{q_{it}^c} > \frac{1 + \tau_t^d}{1 + \tau_t^c}$$

- \iff

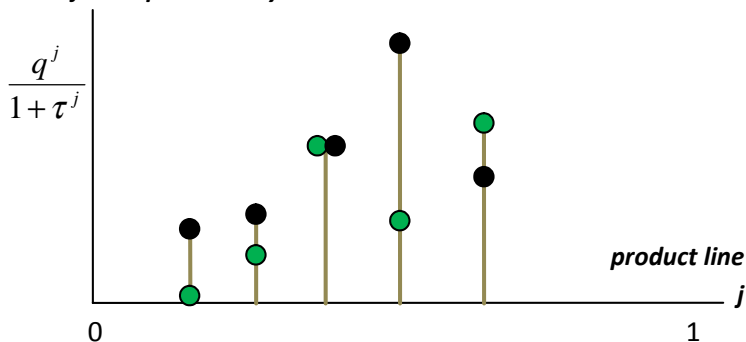
$$\lambda^{n_{it}} > \lambda^{m_{it}}$$

- \iff

$$n_{it} > m_t.$$

Innovation, the Quality Ladder and Dynamics

Tax adjusted productivity



Firms and R&D (I)

- Firm f : collection of leading-edge technologies (Klette & Kortum, 2004).
- u_{ft}^j : # of leading-edge technologies.
- Poisson flow rate of X_t^j innovations:

$$X_t^j = \theta \left(H_t^j \right)^\eta \left(u_t^j \right)^{1-\eta},$$

- H_t^j : number of scientists
- $\eta \in (0, 1)$, and $\theta > 0$.
- Fixed R&D cost of $u_t F_I$ scientists for operation.

Firms and R&D (II)

- Total cost:

$$C_t(u_t, x_t^j) = (1 - s_{lt}^j) w_t^s u_t \left[(x_t^j)^{\frac{1}{\eta}} \theta^{-\frac{1}{\eta}} + F_I \right],$$

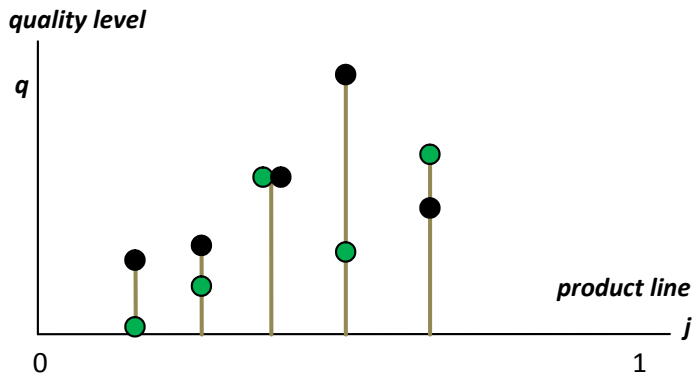
$x_t^j \equiv X_t^j / u_t^j$: innovation intensity.

s_{lt}^j : government subsidy.

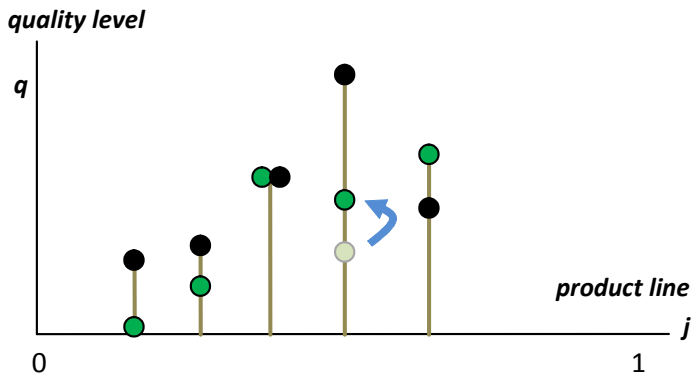
Firms and R&D (III)

- Innovations are *directed* across technologies,
- yet *undirected* within technologies.
- A successful innovation
 - adds a new product line to the firm's portfolio, and
 - leads to one of two types of innovation:
 - 1 *incremental* with probability $1 - \alpha$
 - 2 *breakthrough* with probability α .
- incremental innovation improves quality by $\lambda > 1$.
- breakthrough makes the firm leapfrog the frontier technology.

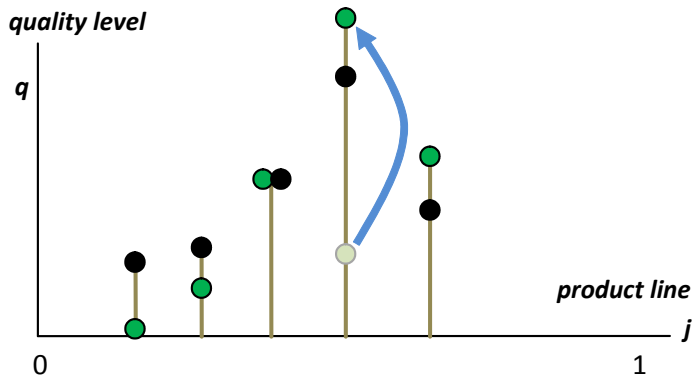
Innovation, the Quality Ladder and Dynamics



Incremental Innovation



Radical Innovation



Free Entry

- Endogenously determined mass of entrants E_t^j invests in R&D by paying fixed cost F_E and the variable cost $\left(X_{Et}^j\right)^{\frac{1}{\eta}} \theta^{-\frac{1}{\eta}}$ in terms of skilled labor and enter at the rate X_{Et}^j .

The Carbon Cycle

- Dirty production y_{it}^d emits κ units of carbon per intermediate output, so total amount of carbon emission is

$$K_t = \int_0^1 \kappa y_{it}^d di.$$

- The atmospheric carbon concentration S_t is (Goloso et al., 2011)

$$S_t = \int_0^{t-T} (1 - d_l) K_{t-l} dl, \quad (2)$$

- where the amount of carbon emitted l years ago still left in the atmosphere is:

$$d_l = (1 - \varphi_P) \left[1 - \varphi_0 e^{-\varphi l} \right]$$

- $\varphi_P \in (0, 1)$: share of permanent emission
- $(1 - \varphi_P) \varphi_0$: transitory component that remains in the first period
- $\varphi \in (0, 1)$: the rate of decay of carbon concentration over time.

Equilibrium Profits (I)

- Unit elastic demand. Thus the profits are

$$\begin{array}{lll}
 \pi_{it}^c = \tilde{Y}_t \frac{\lambda-1}{\lambda} & \pi_{it}^d = 0 & \text{if } m_{it} > n_{it} \\
 \pi_{it}^c = 0 & \pi_{it}^d = \tilde{Y}_t \frac{\lambda-1}{\lambda} & \text{if } m_{it} < n_{it} \\
 \pi_{it}^c = 0 & \pi_{it}^d = 0 & \text{if } m_{it} = n_{it}
 \end{array}$$

where $\tilde{Y}_t \equiv Y_t \exp(\gamma(S_t - \bar{S}))$ is net aggregate output.

Equilibrium Profits (II)

- Not every successful innovation leads to profitable production for two reasons:
 - ① innovation occurs in technology j which is behind technology $-j$,
 - ② potential zero markup if the tax-adjusted labor productivities are the same with the two technologies.
- Probabilities of positive return to a successful innovation:

$$\Gamma_t^c \equiv \sum_{n \leq m} \mu_{nt} + \alpha \left(1 - \sum_{n \leq m} \mu_{nt} \right) \mathbb{I}_{(m \geq 0)}$$

$$\Gamma_t^d \equiv \sum_{n \geq m} \mu_{nt} + \alpha \left(1 - \sum_{n \geq m} \mu_{nt} \right) \mathbb{I}_{(m \leq 0)}$$

Equilibrium Innovation Decision (I)

- Full model: forward-looking innovation decisions.
- Here, let us focus on the cases which firms are **myopic** and maximize instantaneous profits.
- Define the expected value of a successful innovation as

$$\bar{v}_t^j = \Gamma_t^j \pi_{it}^j$$

- Thus equilibrium incumbent innovation decision for $j \in \{c, d\}$:

$$\max_{x_t^j \geq 0} \left\{ x_t^j \bar{v}_t^j - (1 - s_{lt}^j) w_t^s \left[\left(x_t^j \right)^{\frac{1}{\eta}} \theta^{-\frac{1}{\eta}} \left(u_t^j \right)^{\frac{\eta-1}{\eta}} + \mathbb{I}_{(x_t^j > 0)} u_t^j F_l \right] \right\}$$

Equilibrium Innovation Decision (II)

- Conditional on investing in R&D, the equilibrium innovation rate is

$$x_{lt}^j = \left(\frac{\bar{v}_t^j \eta \theta^{\frac{1}{\eta}}}{(1 - s_{lt}^j) w_t^s} \right)^{\frac{\eta}{1-\eta}} = \left(\Gamma_t^j \frac{\lambda - 1}{\lambda} \tilde{Y}_t \frac{\eta \theta^{\frac{1}{\eta}}}{w_t^s (1 - s_{lt}^j)} \right)^{\frac{\eta}{1-\eta}}.$$

Similar for entrant innovation. Increasing in:

- Higher net output (\tilde{Y}_t),
 - higher markups (λ)
 - lower scientists wages (w_t^s)
 - policy*: subsidies to research increase clean innovation (s_{lt}^c).
- Through the Γ_t^j 's,
 - carbon taxes (τ^d) increase clean innovation (reduce dirty innovation).
 - innovation is path-dependent:
 - large technology gaps $\implies \sum_{n \leq m} \mu_{nt}$ very small $\implies \Gamma_t^c$ very small \implies discouraging clean innovation
 - Hence clean innovation will naturally self-reinforce over time.

Empirical Strategy

- Focus on the model would forward-looking behavior.
- The model has 14 parameters/variables to be determined:

$$\{\rho, \bar{S}, \gamma, \varphi, \varphi_0, \varphi_P, \kappa, L^S, \alpha, \eta, \theta, \lambda, F_I, F_E\} \text{ and } \{\mu_{n0}\}_{n=-\infty}^{\infty}$$

- Proceed in four steps:
 - ① external calibration: $\rho, \bar{S}, \gamma, \varphi, \varphi_0, \varphi_P, \kappa$
 - ② direct estimation from micro data: L^S, α, η .
 - ③ match patent data to generate initial distribution: μ_n
 - ④ simulated method of moments: $\theta, \lambda, F_I, F_E$

Data & Sample (I)

- Data:

- Longitudinal Business Database and Economic Censuses,
- National Science Foundation's Survey of Industrial R&D,
- NBER Patent Database.

- Sample:

- Innovators in the US Energy Sector
- Build unbalanced panel with six periods: 1975-1979, . . . , 2000-2004
- Firms must be innovative in first period observed
- Collect operating data, R&D expenditures, and innovations by period

Data & Sample (II)

- Energy sector
 - start with the patent data,
 - classify patents into energy-related patents,
 - classify patents as dirty vs clean using 150,000 USPCs,
 - match patents to firms using name-location matching algorithm,
 - classify firms as dirty vs clean using their patent portfolio,
 - using 400 SIC3, construct dirty and clean patent stock.

Data & Sample (III)

- Sample properties
 - 6228 observations from 1576 firms
 - 19% of all U.S. R&D industrial expenditures
 - 70% of industrial patents for the energy sector

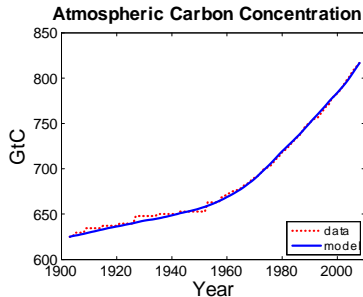
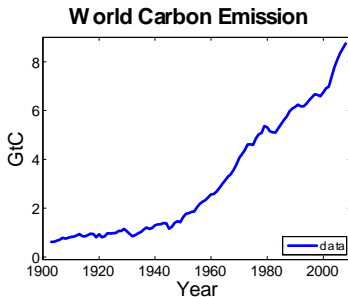
Carbon Cycle Match

We use the following to match the carbon concentration:

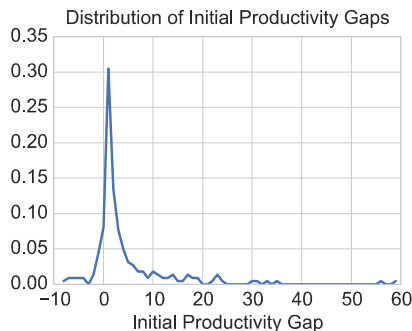
$$S_t = \int_0^{t-1900} (1 - d_l) K_{t-l} dl + S_{1900}, \quad t \in [1900, 2008].$$

where

$$d_l = (1 - \varphi_P) \left[1 - \varphi_0 e^{-\varphi l} \right].$$



Initial Distribution of Technology Gaps



Distribution of initial productivity gaps between clean and dirty technologies across product lines (a positive number indicates a lead for dirty technology)

Clean lead in 6%, and dirty lead in 60% of product lines, but in some cases by quite a lot.

Simulated Method of Moments Estimates

TABLE 2. PARAMETER ESTIMATES

Parameter	Value	Parameter	Value
θ	0.958	F_E	0.040
λ	1.063	R_0	13549
F_I	0.002	ζ	0.016

Note: This table presents the parameter estimates from SMM.

Moments in the Data and Model

TABLE 3. MOMENT MATCHING

Moments	Model	Data	Moments	Model	Data
Entry Share	0.014	0.013	Agg. Growth	0.012	0.012
Exit Rate	0.032	0.018	Emissions ₂₀₀₈	8.461	8.749
R&D/Sales	0.065	0.066	$gEmissions$	0.023	0.024

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Non-targeted Moments

TABLE 4A. ENTRANT SIZE RATIO TO INCUMBENTS

<i>Ratio of Median Sizes</i>		
Size Measure:	Model	Data
Employment	0.18	0.03
Sales	0.18	0.20
Sales per Employee	1.13	1.05

Note: This table compares non-targeted moments in the model and the data.

Non-targeted Moments (continued)

TABLE 4B. COMPARISON OF GROWTH DISTRIBUTION

<i>Employment Growth Probability</i>					
Change 5-Years	Model	Data	Change 5-Years	Model	Data
Decrease 75%	0.25	0.11	Increase 25%	0.26	0.31
Decrease 50%	0.30	0.15	Increase 50%	0.20	0.20
Decrease 25%	0.38	0.26	Increase 75%	0.17	0.14
			Increase 100%	0.10	0.11

Note: This table compares non-targeted moments in model and data.

Climate Dynamics in the Laissez-faire Economy

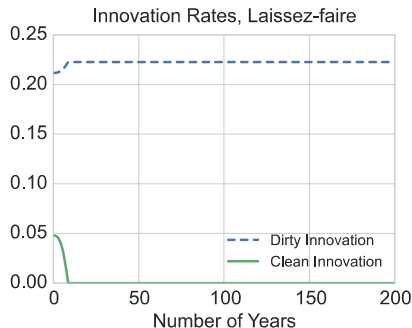


Figure 4. Innovation rates under laissez-faire.

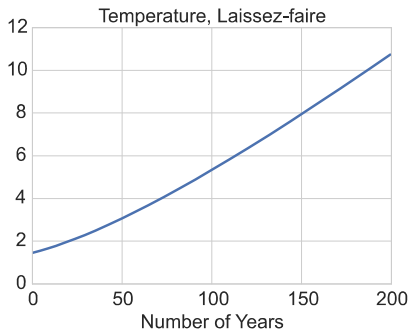


Figure 5. The time path of temperature increases under laissez-faire.

Optimal Policy (I)

- Take a social discount rate of $\rho = 1\%$ (as in Nordhaus's analysis).

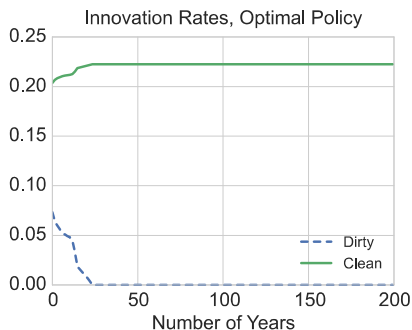


Figure 7. Innovation rates under optimal policies.

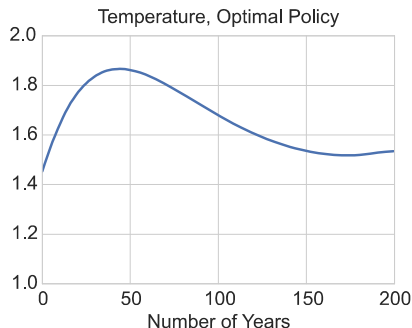


Figure 8. The time path of temperature increases under optimal policies.

Optimal Policy (II)

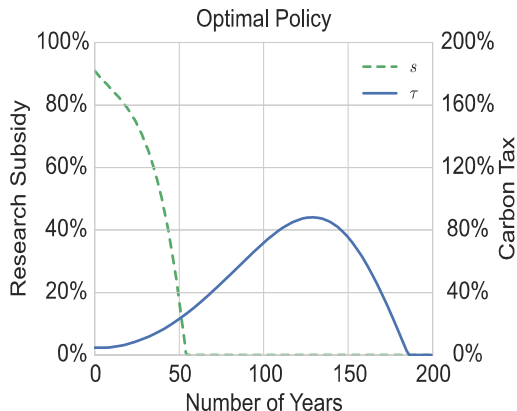


Figure 6. Optimal policies (carbon taxes and research subsidies).

Counterfactual Policy Analysis (I)

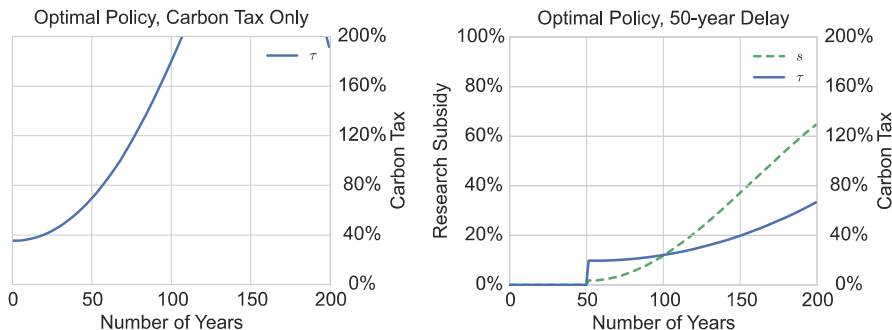


Figure 9. Constrained optimal policies following a 50-year delay and with only carbon taxes; both cost about 2% in terms of consumption

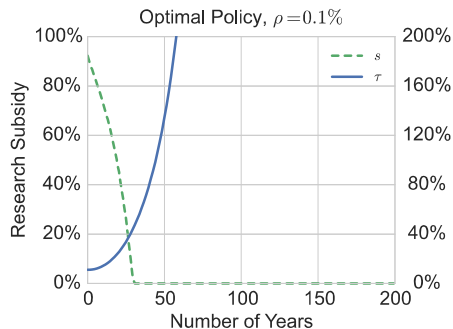
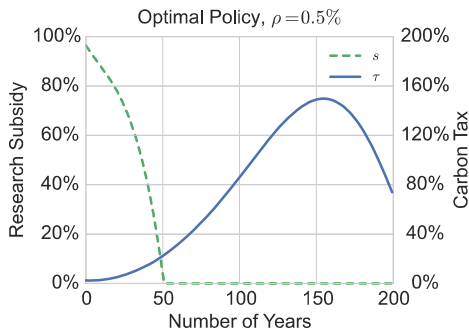


Figure 11. Optimal policies under a social discount rate of 0.5% and 0.1%.

Conclusion

- Optimal policy in the presence of endogenous and directed technological change may rely heavily on R&D subsidy as well as carbon tax.
- Intuition:
 - carbon tax generates static distortion: Leads to reallocation into less productive technology \implies Loss of current consumption
 - R&D subsidy generates dynamic distortion: innovate without any growth for a while until clean takes over.
- Current policy estimates are overtaxing carbon and undersubsidizing R&D.
- Avoiding R&D subsidy can have sizable welfare costs.
- Delaying policy intervention by 50 years can also have very large welfare costs.